

Assignment 5 - Solutions

1/ a) Find $\int_{-\infty}^{\infty} |\operatorname{sinc}(x)|^2 dx$.

By Parseval's Theorem,

$$\begin{aligned}\int_{-\infty}^{\infty} |\operatorname{sinc}(x)|^2 dx &= \int_{-\infty}^{\infty} |\tilde{\operatorname{sinc}}(k)|^2 dk \\ &= \int_{-\infty}^{\infty} \pi^2(k) dk = 1.\end{aligned}$$

b) Find $\int_{-\infty}^{\infty} \operatorname{sinc}(x) dx$.

$$\tilde{\operatorname{sinc}}(k) = \int_{-\infty}^{\infty} \operatorname{sinc}(x) e^{-i2\pi x k} dx.$$

$$\Rightarrow \int_{-\infty}^{\infty} \operatorname{sinc}(x) dx = \tilde{\operatorname{sinc}}(0) = \pi(0) = 1.$$

2/ One example of such a function is any constant function $f(t) = c$, where $c \in \mathbb{R}$.

A more interesting function is

$$f(t) = \begin{cases} \cos(2\pi/t) & t \neq 0 \\ 0 & t = 0 \end{cases}.$$

3/ a) The output of a Linear Shift Invariant system equals

$$y = x * h$$

where h is the impulse response.

When $x(t) = \exp(i2\pi f t)$,

$$\begin{aligned}y(t) &= \int_{-\infty}^{\infty} h(\tau) \exp(i2\pi f(t-\tau)) d\tau \\ &= \exp(i2\pi f t) \int_{-\infty}^{\infty} h(\tau) e^{-i2\pi f \tau} d\tau \\ &= H(f) \exp(i2\pi f t).\end{aligned}$$

This shows that $x(t) = \exp(i2\pi f t)$ is an eigenfunction of any LSI system, and $H(f)$ is its corresponding eigenvalue (where $H = \tilde{\operatorname{f}}$).

b) Consider $f(t) = (g * h)(t)$.

$$g(t) = \int_{-\infty}^{\infty} G(k) e^{i2\pi kt} dt.$$

$$\Rightarrow f(t) = \left(\int_{-\infty}^{\infty} G(k) e^{i2\pi kt} dt \right) * h(t)$$

$$= \int_{-\infty}^{\infty} G(k) \left[e^{i2\pi kt} * h(t) \right] dt \text{ since } * \text{ is linear}$$

$$= \int_{-\infty}^{\infty} G(k) H(k) e^{i2\pi kt} dt \text{ from part (a).}$$

$$\therefore F(k) = \tilde{\mathcal{J}}\{f\}(k) = G(k)H(k).$$

5/ a) $\tilde{\mathcal{J}}\{x + y\} = X + Y \Rightarrow B = \frac{1}{2}$.

b) $\tilde{\mathcal{J}}\{xy\} = X * Y \Rightarrow B = \frac{3}{2}$.

c) $f = x * u \Rightarrow F = X \cdot \tilde{\mathcal{J}}\{u\}$.

$$\tilde{\mathcal{J}}\{u\}(k) = \frac{1}{2} \left[\delta(k) - \frac{i}{\pi k} \right].$$

Since the support of $\tilde{\mathcal{J}}\{u\}$ is \mathbb{R} ,
the bandwidth of F equals that of X ,
which is $\frac{1}{2}$.

d) $g(\gamma) = x(\gamma) \cos(2\pi\gamma)$.

$$\Rightarrow G(k) = X(k) * \frac{1}{2} (\delta(k-1) + \delta(k+1)) \\ = \frac{1}{2} [X(k-1) + X(k+1)].$$

$$\therefore B = \frac{3}{2}.$$

e) $f(\nu) = x(\nu) e^{i2\pi\nu} \Rightarrow F(k) = X(k) * \delta(k+1)$.

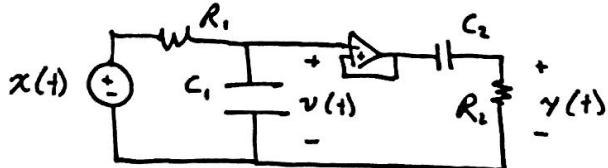
$$\therefore B = \frac{3}{2}.$$

f) $g = (x * y)' \Rightarrow G(k) = (i2\pi k) \tilde{\mathcal{J}}\{x * y\}(k) \\ = (i2\pi k) X(k) Y(k)$.

$$\therefore B = \frac{1}{2}.$$

6) $D = \begin{bmatrix} -1 & 1 & & \\ & -1 & 1 & \\ & & \ddots & \\ & & & -1 & 1 \end{bmatrix} \quad \left. \right\} N-1 \text{ rows}$
 $\underbrace{\hspace{10em}}_{N \text{ columns}}$

7) Review the previous homework for the transfer functions of the first 3 circuits.



$$V(k) = \frac{Z_{c_1} X(k)}{Z_{c_1} + R_1}, \quad \text{where } Z_{c_1}(k) = \frac{1}{j2\pi k C_1}.$$

Since the voltage at both input terminals of the operational amplifier are equal,

$$Y(k) = \frac{R_2}{Z_{c_2} + R_2} V(k) \quad \text{where } Z_{c_2}(k) = \frac{1}{j2\pi k C_2}.$$

$$\therefore H(k) = \frac{Y(k)}{X(k)} = \left(\frac{Z_{c_1}(k)}{Z_{c_1}(k) + R_1} \right) \left(\frac{R_2}{Z_{c_2}(k) + R_2} \right).$$

8) $\omega(s) = -2\pi s.$

$$\begin{aligned} \mathcal{F}^{-1}\{F\}(x) &= \int_{-\infty}^{\infty} F(s) e^{i2\pi s x} ds \\ &= \int_{-\infty}^{\infty} F\left(\frac{\omega}{2\pi}\right) e^{-i\omega x} ds \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{F}(\omega) e^{-i\omega x} d\omega. \end{aligned}$$

$$\begin{aligned} \text{Q1} \quad \int_{-\infty}^{\infty} f(x) \bar{g}(x) dx &= \int_{-\infty}^{\infty} f(x) \mathcal{F}^{-1}\{G(k)\} dx \\ &= \int_{-\infty}^{\infty} f(x) \int_{-\infty}^{\infty} G(k) e^{i2\pi k x} dk dx \\ &= \int_{-\infty}^{\infty} \bar{G}(k) \int_{-\infty}^{\infty} f(x) e^{-i2\pi k x} dx dk \\ &= \int_{-\infty}^{\infty} \bar{G}(k) F(k) dk. \end{aligned}$$